| Chapter 1: Introduction  |  |  |
|--|--|--|
| 1. Which of the following involves reduction in volume of the work?                      |  |  |
| Metal cutting processes  | Metal forming processes                      |  |
| Metal joining processes  | None of the above                            |  |
| 2. Which of the following is used in metal cut   | ting process?                                |  |
| Lathe  | Shaper                                       |  |
| Grinding   | All of above                                 |  |
| 3. The type of finished surface depends on   |  |  |
| Machining technique  | Cutting tool                                 |  |
| Skilled operator   | All the above                                |  |
| 4. Machining techniques are used for   |  |  |
| Metal cutting processes  | Metal forming processes                      |  |
| Metal joining processes  | None of the above                            |  |
| 5. The thickness of metal layer removed is cal   | led depth of cut.                            |  |
| Т  | F  |  |
|  |  |  |
| 6. The unit of cutting speed is  |  |  |
| M  | M/min  |  |
| Km   | Km/hr  |  |
| 7 The cutting speed depends upon   |  |  |
| Work   | Tool   |  |
| Type of finish   | All the above                                |  |
| 8 The distance moved by the tool into the wo   | rkniece for each revolution of work is known |  |
| as   | represe for each revolution of work is known |  |
| Feed   | Cutting speed                                |  |
| Tool life  | None of above                                |  |
| 9 In which operation, the tool moves into the workpiece?                                 |  |  |
| Facing   | Turning                                      |  |
| Drilling   | Grinding                                     |  |
| 10 In which operation, the tool moves only a   | long the surface of workniece?               |  |
| Facing   | Drilling                                     |  |
| Boring   | Taning                                       |  |
| 11. In which of the operation single point out   | ting tool is used?                           |  |
| Lathe work   | Shaping                                      |  |
|  |  |  |
| 12. In which of the operation multi point tool   | All of above                                 |  |
| 12. In which of the operation, multi point tool  |  |  |
| Milling  |  |  |
| Shaping  | Slotting                                     |  |
| 13. The machine tool may be automats with s  | ingle or with multispindle.                  |  |
|  | F  |  |
|  |  |  |
| 14. For a mechanical engineer, to know about machine tool is not so important and can be |  |  |
| avoided.   | avoided.                                     |  |
|  | ۲<br>ا                                       |  |
|  |  |  |
| 15. The CNC machines are   |  |  |
| Outdated   | Productive and Flexible                      |  |

| Non flexible  | Only general purpose                           |  |
|---|--|--|
| 16. The design, operation and maintenance of                                  | each type of machines are dealt by             |  |
| Manufacturing engineering   | Theory of machines                             |  |
| Thermal engineering   | Strength of Material                           |  |
| 17. The different machines are having different                               | nt designs giving variety of job and tool      |  |
| movements.  |  |  |
| Т   | F  |  |
|   |  |  |
| 18. Which of the following needs the study of                                 | Manufacturing Engineering?                     |  |
| To understand design, operations and  | To decide the best alternative machine tool    |  |
| maintenance   |  |  |
| To conduct research and development   | All the above                                  |  |
| program for developing best and more  |  |  |
| efficient machine tools   |  |  |
| 19. To bring about economy and safety in man                                  | nufacturing organizations we need to adopt     |  |
| Computer integrated manufacturing   | Flexible manufacturing system                  |  |
| Automatic guided vehicles for material  | All the above                                  |  |
| handling and robotics   |  |  |
| 20. Every product requires the use of metal cu                                | tting tools, either for manufacturing of       |  |
| products or producing interchangeable parts.                                  | -  |  |
| Т   | F  |  |
|   |  |  |
| 21. Which of the following involves manufact                                  | turing engineering?                            |  |
| Machinery and instruments for raw material                                    | Transportation systems and material            |  |
| processing  | handling devices                               |  |
| Machinery and hand tools for  | All the above                                  |  |
| manufacturing, assembling and packaging                                       |  |  |
| 22. Manufacturing engineering also involves                                   | in chemical plant equipment and cement         |  |
| industries  |  |  |
| Т   | F  |  |
|   |  |  |
| 23. Which of the following production involv                                  | es study of manufacturing engineering?         |  |
| Fasteners   | Transportation vehicles                        |  |
| Cargo vessels and air crafts  | All the above                                  |  |
| 24. Dies for stamping, forming, cutting, piercing and embossing also involves |  |  |
| Manufacturing engineering.  |  |  |
| Т   | F  |  |
|   |  |  |
| 25. Manufacturing engineering is not involved                                 | d in production of electrical machines such as |  |
| motors, generators and alternators  |  |  |
| Т   | F  |  |
|   |  |  |
| 26. The metal machining can be done by using                                  | g which of the following techniques?           |  |
| Mechanical cutting using metal cutting tools                                  | Electrochemical machining                      |  |
| Chemical milling  | All of above                                   |  |
| 27. Which of the following machines are invo                                  | lved in manufacturing of products?             |  |
| Electron bean machining   | Laser beam machining                           |  |
| Plasma arc machining  | All of above                                   |  |
| U   |  |  |

| 28. Suitable training program based on manufacturing engineering for developing skill and |   |  |
|---|---|--|
| knowledge for shop floor duties are to be imparted.                                       |   |  |
| Т   | F   |  |
|   |   |  |
| 29. Manufacturing engineering can lead to   |   |  |
| Construct high precision machine tools  | Producing inter changeable parts using          |  |
|   | precise machine tools                           |  |
| Machinery for mass production which in  | All the above                                   |  |
| turn leads to high wages to employees   |   |  |
| 30. The industry having developed manufactu   | ring engineering can survive in the market by   |  |
| supplying   | -   |  |
| Low quality products at low cost  | Low quality products at high cost               |  |
| High quality products at low cost   | High quality products at high cost              |  |
| 31. Manufacturing engineering does not play   | any role in increasing per capita income of     |  |
| any nation  |   |  |
| Т   | F   |  |
|   |   |  |
| 32. The machine for cutting and shaping metals by means of cutting tools are known as     |   |  |
| Machine tool  | Hand tool                                       |  |
| Press tools   | None of above                                   |  |
| 33. A machine tool changes the shape of mate  | erial by  |  |
| Pressing the job  | Removing the material in form of chips          |  |
| Heating the job   | None of above                                   |  |
| 34. The distance which the tool travels along   | the material in one minute is defined as        |  |
| Cutting speed   | Depth of cut                                    |  |
| Feed  | None of above                                   |  |
| 35. The distance through which the tool advar   | aces into the machine during one revolution is  |  |
| defined as  | lees into the indefine during one revolution is |  |
| Cutting speed   | Depth of cut                                    |  |
| Feed  | None of above                                   |  |
| 36. The volume of metal removed in unit time  | is defined as                                   |  |
| Metal removal rate  | Metal deposition rate                           |  |
| Metal cutting rate  | None of above                                   |  |
| 27 The time required to remove specified que  | notice of above                                 |  |
| 37. The time required to remove specified quantity of material from the workpiece can be  |   |  |
| Faed  | Depth of out                                    |  |
| Matal removal rate  | None of above                                   |  |
| 28. To reduce the machining cost the metal sh   | hould be removed by                             |  |
| 38. To reduce the machining cost the metal should be removed by                           |   |  |
| Cutting rapidly   | Not at all autting                              |  |
| Cutting with hands  | Not at all cutting                              |  |
| 39. The cutting tool should be  | Duon outra shorm on od                          |  |
| Made of proper material   | Property sharpened                              |  |
| Held rigidly  | All the above                                   |  |
| 40. 10 keep the wastage to its minimum limit  | one must  |  |
| Prevent damage to the tool only   | Prevent damage to the workpiece only            |  |
| Prevent damage to tool and workpiece both Not preventing the damage                       |   |  |
| 41. The metal removal rate is related to  |   |  |
| Volume of metal removed in unit time  | Area of metal removed in unit time              |  |

| Length of metal removed in unit time                               | None of above.                        |  |
|--|---------------------------------------|--|
| 42. The volume of metal removed in unit time                       | e is measured in unit.                |  |
| Cm/min   | Cm <sup>2</sup> /min                  |  |
|  |                                       |  |
| Cm <sup>3</sup> /min   | None of above                         |  |
| 43. As per IS the rough surface finish is denoted                  | ted by the symbol                     |  |
| $\nabla$   | Δ                                     |  |
| α  | θ                                     |  |
| 44. The symbol used for fine machining is                          |                                       |  |
| $\nabla \nabla$  | $\nabla$                              |  |
| $\nabla \nabla \nabla$   | None of above                         |  |
| 45. The shop floor supervisor himself does the machining of metals |                                       |  |
| Т  | F                                     |  |
|  |                                       |  |
| 46. What are the quality required for a shop fl                    | oor supervisor?                       |  |
| Democratic leadership  | Result consciousness                  |  |
| Correct judgement  | All the above                         |  |
| 47. A supervisor is a link between the management and the workers. |                                       |  |
| Т  | F                                     |  |
|  |                                       |  |
| 48. The supervisor does not need to                                |                                       |  |
| Instruct and train the worker                                      | Know how to supervise and control the |  |
|  | workers.                              |  |
| Machining the workpiece by himself                                 | Know the labor psychology             |  |
| 49. A supervisor must have the following skills                    |                                       |  |
| Education  | Maturity                              |  |
| Group spirit   | All the above                         |  |
| 50. A supervisor should be open minded and flexible.               |                                       |  |
| Т  | F                                     |  |
|  |                                       |  |

| Chapter 2: Grinding and super finishing processes                  |  |
|--|--|
| 1. Grain number of grinding wheel is to grain size.                |  |
| a) Directly proportional   |  |
|  | b) Inversely proportional                |
| c) Does not depend   |  |
|  | d) None of the mentioned                 |
| 2. The grinding operation is                                       |  |
| Shaping operation  | Forming operation                        |
| Surface finishing operation  | Dressing operation                       |
| 3. The material removal rate in grinding operation is small due to |  |
| Only a small portion of abrasive are                               | Positive rake angle                      |
| involved in cutting  |  |
| Zero rake angle  | Material removal rate does not depend on |
|  | the rake angle                           |

| 4. The material removal rate of the grinding process in comparison to the material removal  |  |  |
|---|--|--|
| rate in facing on a lathe is  |  |  |
| Small   | Large  |  |
| Same  | Cannot say                                   |  |
| 5. Grinding ratio generally lies between  |  |  |
| 0.5 - 10  | 100 - 200                                    |  |
| 1000 - 2000   | 30 - 40                                      |  |
| 6. The grinding wheel speed (surface speed in   | m/min) usually varies from                   |  |
| 500 - 1000  | 1000 - 15000                                 |  |
| 1500 - 2000   | 2000 - 2500                                  |  |
| 7. The work or surface speed for cylindrical g  | rinding varies from                          |  |
| 5 – 10 m/min  | 10 – 20 m/min                                |  |
| 20 – 30 m/min   | 40 - 60 m/min                                |  |
| 8. In grinding of irregular, curved, tapered, co  | nvex and concave surfaces, the grinder used  |  |
| is  |  |  |
| Cylindrical grinder   | Internal grinder                             |  |
| Surface grinder   | Tool and cutter grinder                      |  |
| 9. Surface grinding is done to produce  |  |  |
| Tapered surface   | Flat surface                                 |  |
| Internal cylindrical holes  | None of these                                |  |
| 10. The method of grinding used to produce a straight or tapered surface on a work piece is |  |  |
| Internal cylindrical grinding   | Form grinding                                |  |
| External cylindrical grinding   | Non cylindrical grinding                     |  |
| 11. In centerless grinding, the surface speed of regulating wheel is                        |  |  |
| 5 - 15 m/min  | 15 - 35 m/min                                |  |
| 15 - 60 m/min   | 90 - 120 m/min                               |  |
| 12. In centralized grinders, the regulating wheel is inclined at                            |  |  |
| 0 - 8 degree  | 9 - 15 degree                                |  |
| 16 - 20 degree  | 21 - 25 degree                               |  |
| 13. In centerless grinding, workplace center w  | vill be                                      |  |
| Above the line joining the two-wheel  | Below the line joining the two-wheel         |  |
| centers   | centers                                      |  |
| On the line joining the two-wheel centers   | At the intersection of the line joining the  |  |
| , ,   | two-wheel centers with the workplace plane   |  |
| 14. Which of the following parameters influence the axial feed rate in centerless grinding? |  |  |
| Regulating wheel diameter   | Speed of the regulating wheel                |  |
| Angle between the axes of grinding and  | All the above                                |  |
| regulating wheels   |  |  |
| 15. The method of centerless grinding used to   | produce taper is                             |  |
| In feed grinding  | Through feed grinding                        |  |
| End feed grinding   | Any one of these                             |  |
| 16. In centreless grinders, the maximum angular adjustment of the regulating wheel is       |  |  |
| 5 deg   | 10 deg                                       |  |
| 15 deg  | 20 deg                                       |  |
| 17. The snag grinding is done to remove a cor   | nsiderable amount of metal without regard to |  |
| the accuracy of the finished surface  |  |  |
| Т   | F  |  |
|   |  |  |
|   |  |  |

| 18. Trimming the surface left by sprues and risers on castings is the example of snag    |  |  |
|--|--|--|
| grinding   |  |  |
| <u> </u>   | F  |  |
|  |  |  |
| 19. Removing flash on forgings is the exampl   | e of snag grinding                             |  |
| Т  | F  |  |
|  |  |  |
| 20. The grinding of long, slender shafts or bar  | s is usually done by                           |  |
| In feed grinding   | Through feed grinding                          |  |
| End feed grinding  | Any one of these                               |  |
| 21. The in-feed grinding is used to  |  |  |
| Produce tapers   | Grind shoulders and formed surfaces            |  |
| Grind long, slender shafts or bars   | None of these                                  |  |
| 22. The method of grinding used to produce in  | nternal cylindrical holes and tapers is        |  |
| Internal cylindrical grinding  | Form grinding                                  |  |
| External cylindrical grinding  | Surface grinding                               |  |
| 23. An open structure of a grinding wheel is u   | used for                                       |  |
| Soft materials   | Tough materials                                |  |
| Ductile materials  | All of these                                   |  |
| 24. Which of the following grinding wheel we   | ould be more economical for grinding of hard   |  |
| workpiece?   |  |  |
| Open structure grinding wheel  | Dense structure wheel                          |  |
| Both of above  | None of above                                  |  |
| 25. Which of the following grinding wheel we   | ould be more economical for grinding of soft   |  |
| workpiece?   |  |  |
| Open structure grinding wheel  | Dense structure wheel                          |  |
| Both of above  | None of above                                  |  |
| 26. Which of the following grinding machine  | will give a better result for rough machining? |  |
| a) Fine grain  |  |  |
|  | b) Very fine grain                             |  |
| c) Coarse grain  |  |  |
|  | d) None of the mentioned                       |  |
| 27. Which of the following grinding machine  | will give a better result for finish machining |  |
| operation?   |  |  |
| a) Fine grain  |  |  |
|  | b) Medium grain                                |  |
| c) Coarse grain  |  |  |
|  | d) None of the mentioned                       |  |
| 28. Which of the following symbol's range of alphabet represent soft grain in grinding   |  |  |
| wheel?   |  |  |
| a) A – H   |  |  |
|  | b) I – P                                       |  |
| c) Q – T   |  |  |
|  | d) T – Z                                       |  |
| 29. Which of the following symbol's range of alphabet represent medium hardness grain in |  |  |
| grinding wheel?  |  |  |
| a) A – H   |  |  |
|  | b) I – P                                       |  |

| c) Q – T  |   |
|---|---|
|   | d) T – Z  |
| 30. Which of the following represents the cor   | rect symbol of vertified bond in a              |
| specification of grinding wheel?  |   |
| V   | R   |
| В   | S   |
| 31. Which of the following represents the cor   | rect symbol of rubber bond in a specification   |
| V   | R   |
| B   | S   |
| 32 Which of the following represents the cor  | rect symbol of Silicate bond in a specification |
| of grinding wheel?  |   |
| V   | R   |
| В   | S   |
| 33. A dense structure of a grinding wheel is u  | sed for   |
| Hard materials  | Brittle materials                               |
| Finishing cuts  | All of these                                    |
| 34. Which of the following represents the cor   | rect symbol of resin bond in a specification of |
| grinding wheel?   |   |
| V   | R   |
| В   | S   |
| 35. In order to grind soft material a coarse-gra  | ained wheel is used.                            |
| Т   | F   |
|   |   |
| 36. The hardness of a grinding wheel is speci-  | fied by   |
| Brinell hardness number   | Rockwell hardness number                        |
| Vickers pyramid number  | Letter of alphabet                              |
| 37. The size of the abrasive grain required in  | a grinding wheel depends upon the hardness      |
| of the material to be grinded.  |   |
| Т   | F   |
|   |   |
| 38. The grade of grinding wheel depends upo   | n   |
| The hardness of the material being grinded  | Speed of wheel and work                         |
| Condition of grinding machine   | All of these                                    |
| 39. The structure of grinding wheel depends u   | ipon  |
| The hardness of the material being grinded  | Nature of the grinding operation                |
| Finish required   | All of these                                    |
| 40. Soft material cannot be economically grinded due to   |   |
| High temperature involved   | Frequent wheel clogging                         |
| Rapid wheel wear  | Low work piece stiffness                        |
| 41. Glazing in grinding wheel takes place when the wheel is too hard or wheel revolves at a very high speed |   |
| T   | f   |
| 1   | L   |
| 42 Glazing in grinding wheel can be decrease  | ed by using a softer wheel or by decreasing     |
| the wheel speed.  |   |
| Т   | F   |
|   |   |

| 43. Removing dull grains in order to make grinding wheel sharp is known as           |  |  |
|--|--|--|
| Loading  | Dressing                                   |  |
| Unloading  | None of above                              |  |
| 44. In grinding wheel the cutting edge takes a                                       | glass like appearance (glazing) due to     |  |
| Wear of bond   | Cracks on grinding wheel                   |  |
| Wear of abrasive grains  | None of above                              |  |
| 45. Operation done to make the periphery of g  | grinding wheel concentric with its axis to |  |
| recover its lost shape is known as   |  |  |
| Trueing  | Loading                                    |  |
| Unloading  | None of above                              |  |
| 46. Grinding wheel should be tested for balance                                      |  |  |
| Only once when manufactured  | Only at the end of grinding operation      |  |
| Very occasionally  | Never be tested                            |  |
| 47. Crack in grinding wheel is developed due to low speed of the wheel               |  |  |
| Т  | F  |  |
|  |  |  |
| 48. Honing and Lapping are not the surface finishing processes.                      |  |  |
| Т  | F  |  |
|  |  |  |
| 49. The abrasive recommended for grinding materials of low tensile strength is       |  |  |
| Silicon carbide  | Aluminum oxide                             |  |
| Sandstone  | Diamond                                    |  |
| 50. The silicon carbide is chiefly used for grinding low tensile strength materials. |  |  |
| Т  | F  |  |

| Chapter 3: Gear manufacturing and finishing processes                                  |             |  |
|--|-------------|--|
| 1. Thickness of tooth measured along the pitch circle is known as                      |             |  |
| a) Tooth thickness   |             |  |
|  | b) Backlash |  |
| c) Face width  |             |  |
|  | d) Top land |  |
| 2. Difference between space width and the thickness of tooth along the pitch circle is |             |  |
| known as   |             |  |
| a) Tooth thickness   |             |  |
|  | b) Backlash |  |
| c) Face width  |             |  |
|  | d) Top land |  |
| 3. Length of tooth parallel to gear axis is known as                                   |             |  |
| a) Tooth thickness   |             |  |
|  | b) Backlash |  |
| c) Face width  |             |  |
|  | d) Top land |  |
| 4. Top surface of tooth is known as  |             |  |
| a) Tooth thickness   |             |  |
|  | b) Backlash |  |

| c) Face width   |   |  |
|---|---|--|
|   | d) Top land                                   |  |
| 5. Bottom surface of the tooth between two ac                                     | ljacent fillets is known as                   |  |
| a) Flank  |   |  |
|   | b) Face                                       |  |
| c) Bottom Land  |   |  |
|   | d) None of the above                          |  |
| 6. Surface of tooth between pitch circle and to                                   | pp land is known as                           |  |
| a) Flank  |   |  |
|   | b) Face                                       |  |
| c) Bottom Land  |   |  |
|   | d) Fillet                                     |  |
| 7. Tooth surface between pitch circle and the                                     | bottom land including fillet is known as      |  |
| a) Flank  |   |  |
|   | b) Face                                       |  |
| c) Top Land   | 1) D1-11                                      |  |
| Q. Commentary of the test of flexity of the                                       | d) Backlash                                   |  |
| 8. Curved portion of the tooth flank at the roo                                   | t circle is known as                          |  |
| a) Fillet   | h) Face                                       |  |
| a) Top Lond   | b) Face                                       |  |
| c) Top Land   | d) Bottom land                                |  |
| 9 Force everted by driving tooth on the drive                                     | a) Bottom failed                              |  |
| point of contact of two teeth is known as   | in tooth along the line of pitch point to the |  |
| a) Line of Action   |   |  |
|   | b) Path of contact                            |  |
| c) Arc of contact   |   |  |
|   | d) Angle of action                            |  |
|   |   |  |
| 10. Angle between the pressure line and the c                                     | ommon tangent to the pitch circle is known as |  |
| a) Pressure angle   |   |  |
|   | b) Path of contact angle                      |  |
| c) Arc of contact angle   |   |  |
|   | d) Angle of action                            |  |
| 11. Backlash of gear is given by  |   |  |
| a) Space width – Tooth Thickness*2  |   |  |
|   | b) Space width / Tooth Thickness              |  |
| c) Space width – Tooth Thickness  |   |  |
|   | d) Space width * Tooth Thickness              |  |
| 12. Ratio of speed of the follower to the speed of driving gear is known as       |   |  |
| a) Gear ratio   |   |  |
|   | b) Module                                     |  |
| c) Velocity ratio   |   |  |
|   | d) None of the mentioned                      |  |
| 13. The ratio of diameter of follower to the diameter of driving gear is known as |   |  |
| a) Gear ratio   |   |  |
|   | b) Module                                     |  |
| c) velocity ratio   |   |  |
|   | a) None of the mentioned                      |  |

| 14. Velocity ratio is the inverse of gear ratio  |  |  |
|--|--|--|
| Т  | F  |  |
|  |  |  |
| 15. Angle subtended by circular pitch at the c   | entre of pitch circle is known as          |  |
| a) Pitch angle   |  |  |
|  | b) Addendum angle                          |  |
| c) Module angle  |  |  |
|  | d) None of the mentioned                   |  |
| 16. Which of the following is not a standard p   | ressure angle in degree?                   |  |
| a) 20  | b) 25                                      |  |
|  |  |  |
| c) 14.5  |  |  |
|  | d) 19                                      |  |
| 17. Distance between the points of contact of  | two mating teeth from the beginning of     |  |
| engagement to the end of engagement is know  | vn as                                      |  |
| a) Arc of contact  |  |  |
|  | b) Path of contact                         |  |
| c) Path of approach  |  |  |
|  | d) Path of recess                          |  |
| 18. Path of contact from the beginning of eng  | agement to the pitch point is known as     |  |
| a) Arc of contact  |  |  |
|  | b) Path of contact                         |  |
| c) Path of approach  |  |  |
|  | d) Path of recess                          |  |
| 19. Portion of path of contact from the pitch p  | ooint to end of engagement is known as     |  |
| a) Arc of contact  |  |  |
|  | b) Path of contact                         |  |
| c) Path of approach  | d) Dath of reason                          |  |
| 0) Faul 01 recess  |  |  |
| 20. Circumferential distance between points from the beginning to the end of engagement  |  |  |
| a) Are of contact  | 5  |  |
| a) Are of contact  | b) Path of contact                         |  |
| a) Path of approach  |  |  |
| c) I all of approach   | d) Path of recess                          |  |
| 21 Portion of arc of contact from the beginning  | ng of the engagement to the pitch point is |  |
| 21. Portion of arc of contact from the beginning of the engagement to the pitch point is |  |  |
| a) Contact ratio   |  |  |
|  | b) Angle of friction                       |  |
| c) Arc of recess   |  |  |
|  | d) Arc of approach                         |  |
| 22. Portion of arc of contact from the pitch po  | int to the end of engagement is known as   |  |
| a) Contact ratio   |  |  |
|  | b) Angle of friction                       |  |
| c) Arc of recess   | -,   |  |
| ,  | d) Arc of approach                         |  |
| 23. Angle subtended by arc of contact at the centre of pitch circle is known as          |  |  |
| a) Contact ratio   |  |  |
|  | b) Angle of action                         |  |
|  |  |  |

| c) Arc of recess   |  |  |
|--|--|--|
|  | d) Arc of approach                             |  |
| 24. Number of teeth in contact is given by   |  |  |
| a) Contact ratio   | b) Angle of ection                             |  |
| (a) Ara of recess  | b) Angle of action                             |  |
| c) Arc of recess   | d) Arc of approach                             |  |
| 25 Contact ratio is given by   |  |  |
| a) Angle of action/pitch angle   | b) Angle of action*pitch angle                 |  |
| c)Angle of action-pitch angle  | d) Angle of action +pitch angle                |  |
|  |  |  |
| 26. Which of the following is a standard pressure angle in degree?                 |  |  |
| 20   | 21   |  |
| 13.5   | 19   |  |
| 27. The path of contact between the points of contact of two mating teeth from the |  |  |
| beginning of engagement to the end of engage                                       | ement is known also as contact length.         |  |
| Т  | F  |  |
|  |  |  |
| 28. Imaginary friction cylinders which by put                                      | e rolling together transmit the same motion as |  |
| a) Ditab avlindara   | T  |  |
| a) Fitch cynhaets  | b) Pitch diameter                              |  |
| c) Pitch circle  |  |  |
|  | d) Pitch point                                 |  |
| 29. Circle which corresponds to section of eq                                      | uivalents pitch cylinder by a plane normal to  |  |
| wheel axis is known as   |  |  |
| a) Pitch cylinders   |  |  |
|  | b) Pitch diameter                              |  |
| c) Pitch circle  |  |  |
|  | d) Pitch point                                 |  |
| 30. Diameter of pitch cylinder is known as   |  |  |
| a) Pitch cylinders   |  |  |
|  | b) Pitch diameter                              |  |
| c) Pitch circle  | d) Pitch point                                 |  |
| 31 Two different nitch circles generally meet                                      | a) i nen point                                 |  |
| a) Pitch cylinders   |  |  |
|  | b) Pitch diameter                              |  |
| c) Pitch circle  |  |  |
|  | d) Pitch point                                 |  |
| 32. Line passing through center of rotation of two meeting gear is known as        |  |  |
| a) Pitch   |  |  |
|  | b) Rack  |  |
| c) Pinion  |  |  |
|  | d) Line of centre                              |  |
| 33. Driving gear of two mating gear which is generally small is known as           |  |  |
| a) Pitch   |  |  |
|  | b) Rack  |  |

| c) Pinion  |  |  |
|--|--|--|
|  | d) Line of centre  |  |
| 34. Gear wheel of infinite diameter can be considered as Rack  |  |  |
| Т  | F  |  |
|  |  |  |
| 35. Part of pitch circle of rack which is a strai  | ght line is also known as                                  |  |
| a) Pitch line  |  |  |
|  | b) Rack  |  |
| c) Pinion  |  |  |
|  | d) pitch circle  |  |
| 36. Ratio of circumference of pitch circle to number of teeth is known as  |  |  |
| a) Circular pitch  | b) Diametral pitch   |  |
|  |  |  |
| c) Rack  |  |  |
|  | d) Pitch line  |  |
| 37. Distance measured along the circumference  | ce of pitch circle from a point on tooth to the            |  |
| corresponding point on adjacent tooth is know  | /n as  |  |
| a) Circular pitch  | b) Diametral pitch   |  |
|  |  |  |
| c) Rack  |  |  |
| ,  | d) Pitch line  |  |
| 38. Number of teeth divided by length of pitch circle diameter is known as   |  |  |
| a) Circular pitch  | b) Diametral pitch   |  |
|  | c) <u></u>   |  |
| c) Rack  |  |  |
|  | d) Pitch line  |  |
| 39 Ratio of pitch diameter in mm to the number of teeth is known as  |  |  |
| a) Circular pitch  | b) Diametral pitch   |  |
|  | o) Dianeara pien   |  |
| c) Module  |  |  |
|  | d) Pitch line  |  |
| 40 Module of two mating gears can be of any  | v value  |  |
| T  | F  |  |
| 1  | 1  |  |
| 41 Potic of number of teath on goor to the number of teath on ninion is known as   |  |  |
| a) Circular pitch  | h) Diametral nitch   |  |
| a) Circular pitch  | b) Diametral pich  |  |
| c) Gear ratio  |  |  |
|  | d) Ditch line  |  |
| 42 Patie of angular valueity of the follower t   | a) Fitch line  |  |
| 42. Kauo of angular velocity of the follower to the angular velocity of driving gear is  |  |  |
| a) Circular pitch  | h) Diamatral nitch   |  |
| a) Circular pitch  | Diametral plich  |  |
|  | , <b>1</b>   |  |
| a) Valogity ratio  |  |  |
| c) Velocity ratio  | d) Ditch line  |  |
| c) Velocity ratio  | d) Pitch line  |  |
| <ul> <li>c) Velocity ratio</li> <li>43. What is the effect of improper alignment of the property of the proper</li></ul> | d) Pitch line<br>of each tooth?                            |  |
| <ul><li>c) Velocity ratio</li><li>43. What is the effect of improper alignment of a) Tooth thickness increases</li></ul>   | d) Pitch line<br>of each tooth?<br>b) Face width decreases |  |

| c) I oad will not be distributed evenly   |                           |  |
|---|---------------------------|--|
| c) Load will not be distributed evening   | d) Pitch of teeth reduced |  |
| 4. When the teeth of geer are not concentric, the velocity will fluctuate             |                           |  |
| T   | E                         |  |
|   | <u>Г</u>                  |  |
|   |                           |  |
| 45. Which of the following element is not determined by analytical inspection?        |                           |  |
| a) Profile  |                           |  |
|   | b) Noise level            |  |
| c) Spacing  |                           |  |
|   | d) Pitch                  |  |
| 46. By analytical inspection method all the individual elements of the gear teeth are |                           |  |
| checked.  | C C                       |  |
| Т   | F                         |  |
|   |                           |  |
| 47. Which of the following is not determined by the functional type of inspection?    |                           |  |
| Lead  | Noise level               |  |
| Variation in action   | Vibration                 |  |
| 48. Rolling test is generally performed on Par  | kson gear tester          |  |
| Т   | F                         |  |
|   |                           |  |
| 49. Another name for Wobble   |                           |  |
| a) Radial run-out   |                           |  |
|   | b) Eccentricity           |  |
| c) Composite error  |                           |  |
|   | d) Axial run-out          |  |
| 50. Eccentricity is the radial runout, measured along perpendicular to the rotation   |                           |  |
| axis.   |                           |  |
| Half  | Double                    |  |
| Three times   | Four times                |  |